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UNITED STATES PATENT APPLICATION

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of

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for

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MACHINE FOR MANUFACTURING A CAPITAL FOR AN ARCHITECTURAL COLUMN

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BACKGROUND OF THE INVENTION

FIELD OF THE INVENTION

This invention relates to a machine used to rotate the mold of a capital for an architectural column in the process of manufacturing a capital from elastomers and foams or elastomer-foam combinations. As used throughout this document, the term "elastomer" is meant also to include a "resin"; and the term "foam" includes any liquid that will expand and create a lightweight filler.

DESCRIPTION OF THE RELATED ART

The inventor is unaware of any patents relating to a machine used for rotating molds for architectural structures to produce elastomer or elastomer-foam products.

Traditionally, due to the difficulty in working with elastomers or both elastomers and foam, capitals for architectural columns have not been manufactured from these materials. The process for making such capitals preferably involves rotation, as described in copending United States patent application serial no. 09/862,893, filed on 05/22/2001. And it is further preferable to accomplish such rotation with a machine.

It is assumed by the inventor that a machine to aid in the process of making capitals for architectural columns from elastomers or both elastomers and foam, has not been constructed due to the difficulty presented in finding and/or utilizing a process by which capitals could be produced using these materials, with or without the machine, resulting in a desirable outcome.

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Rotation of the mold can be accomplished in any manner but due to the difficulty of rotating the mold by hand it is preferably done by machine.

The shaft is removably attached to the mold of the capital.

Preferably, the shaft extends symmetrically about the point of rotation, or fulcrum for rotation, for the first, preferably the pitch, axis. This permits a mold to be attached at each end of the shaft and thereby balances the load on the shaft.

BRIEF DESCRIPTION OF THE DRAWINGS

Figure 1 depicts a typical setup which allows the capital mold to be attached to the Machine.

Figure 2 depicts one possible machine design that will rotate a mold upon two axes to aid in the process of making capitals from elastomers or both elastomers and foam.

Figure 3 depicts the same Machine design as that of figure 2, but from a different viewpoint.

Figure 4 depicts another possible Machine design that will rotate a mold upon two axes to aid in the process of making capitals from elastomers or both elastomers and foam.

Figure 5 depicts the same Machine design as that of figure 4, but from a different viewpoint.

Figure 6 depicts yet another possible Machine design that will rotate a mold upon two axes to aid in the process of making capitals from elastomers or both elastomers and foam.

Figure 7 depicts the same Machine design as that of figure 6, but from a different viewpoint.

upon the machine (Figures 2-7) is provided by any number of possible arrangements of machinery which may be composed of, but not limited to: motors, belts, chains, levers, gears, transmissions, and differentials. Figures 2-7 show three examples different Machine designs that can be used. The critical feature is that the Machine rotate the mold 1 about multiple axes, preferably two and preferably substantially orthogonal axes.

A description of the components and the functions of these components for the three exemplary Machines, which produce the desired result (i.e., rotation of the mold 1 upon two axes), follows. In each of the drawings for these examples the belts and/or chains (whichever is preferred) which attach one pulley to another have not been drawn in order to allow a clear view of the other components of each machine. It will be assumed that they are there and do exist, though not drawn, for it is by these belts and/or chains which energy is transferred from one point to another in the machine system.

Figure 2 and figure 3 show the same Machine 7 at different angles, this Machine 7 being one of the possibilities to achieve rotation upon two axes. In this Machine 7 the pulley 8 of a motor 9 is used to turn the pulley 10 of a differential 11 which in turn rotates another pulley 12 of that differential 11. That pulley 12 of the differential 11 then rotates a different pulley 13 which is attached and fixed rigidly to a bar 14. This bar 14 then rotates precisely with the rotation of this pulley 13. Upon another part of the bar 14 is also rigidly fixed a lever arm 15. As the bar 14 rotates, the lever arm 15 rotates precisely with it. At another point upon this lever arm 15 is freely attached second lever arm 16 allowing the second lever arm 16 to rotate freely about a pin 17 which attaches it to the first lever arm 15, and upon a plane parallel to the first lever arm 15. At another place on this second lever arm 16 is freely attached a second pin 18 which is rigidly attached to a table 19. This table 19 is supported by two bars 20. Through these bars 20, and through the center of the table 19, passes a third pin 21, allowing the table 19 to freely rotate about this pin 21. Hence as the pulley 13 attached to the bar 14 is rotated, and in turn rotates both the first lever 15 arm and the second lever arm 16, the table 19 is rotated, or pivoted, about the third pin 21. This is due to the second pin 18 which attaches the second lever arm 16 to the table 19. This angular motion, the table 19 pivoting about the third pin 21, gives the mold 1 attached to the shaft 2 rotation about the pitch axis. To obtain rotation about a second axis a second motor 22 is placed upon the table 19 which rotates the bar ends 2 orthogonally to

1 the pivoting motion of the table **19** about the third pin **21**, *i.e.*, about the roll axis. The angular
 2 velocity of the rotation of the ends of the shaft **2** is controlled and can be changed by a
 3 transmission **23** mounted also upon the table **19**. The angular velocity of the rotation of the table
 4 **19** about the third pin **21** is controlled by the speed of the first motor **9**. This is desirable since
 5 adjustments of the velocities of rotation about the axis is preferred.

6 In Figure 4 and Figure 5 a second Machine **24** design possibility is presented. Here, the
 7 pulley **8** of a motor **9** turns the pulley **10** of a differential **11** which in turn rotates another pulley
 8 **12** of the differential **11**. The rotation of the second pulley **12** of the differential **11** rotates a
 9 lever arm **15**. This lever arm **15** in turn rotates a second lever arm **16** as it is freely attached to
 10 that second lever arm **16** by a pin **17** (as previously described with the first machine **7** design
 11 possibility above). As it is attached to a table **19** by a second pin **18** (as previously described
 12 with the first machine **7** design possibility above) the movement of the second lever arm **16**
 13 causes the table **19** to pivot about a third pin **21**. This third pin **21** passes through both two
 14 supporting bars **20** and the table **19** (as previously described with the first machine **7** design
 15 possibility above). This allows for rotation about the pitch axis. For the rotation about a second
 16 axis, the pulley **25** of a second motor **26**, which can, but not necessarily is, fixed on top of a
 17 differential **27** which is fixed to the table **19**, turns the pulley **28** of the differential **27**. The
 18 differential **27** then rotates the shaft **2** upon which are the molds **1** in the roll axis. The velocities
 19 of the rotations about the different axes are controlled by the speed of the first motor **9** and the
 20 second motor **26**, respectively. The speeds of the first motor **9** and the second motor **26** can be
 21 controlled by a control box **29**.

22 Figure 6 and Figure 7 represent yet a third possibility of a machine **30** used to rotate the
 23 capital molds **1** about two axes. In these figures the pulley **8** of a motor **9** turns the pulley **10** of a
 24 differential **11** which in turn rotates another pulley **12** of the differential **11**. The rotation of the
 25 second pulley **12** of the differential **11** rotates a lever arm **15**. This lever arm **15** in turn rotates a
 26 second lever arm **16** since it is freely attached to that second lever arm **16** by a pin **17** (as
 27 previously described with the first machine **7** design possibility above). Since it is attached to a
 28 table **19** by a second pin **18** (as previously described with the first machine **7** design possibility
 29 above), the movement of the second lever arm **16** causes the table **19** to pivot about a third pin
 30 **21**. This third pin **21** passes through both two supporting bars **20** and the table **19** (as previously

1 described with the first machine 7 design possibility above). This allows for rotation about the
2 pitch axis. For rotation about a second axis the pulley 31 of a second motor 32 mounted
3 preferably, but not necessarily, to the underneath of the table 19 rotates a pulley 33 through
4 which passes the shaft 2. The rotation of this pulley 33 rotates the shaft 2 in the roll axis. The
5 velocities of the rotations about the different axes are controlled by the speed of the first motor 9
6 and the second motor 32, respectively. The speeds of the first motor 9 and the second motor 32
7 can be controlled by a control box 29.

8 Rotation about a third substantially orthogonal (to both the first axis and the second axis)
9 axis, the yaw axis in the preceding examples, could be accomplish simply by attaching a motor
10 that provides rotary motion to the supporting bars 20.

11 The pitch, roll, and yaw axes are used herein to denote the same axes are they signify in
12 the case of airplanes.

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